

2D and 3D validation of a hybrid method based on A and H formulations for Pulsed Field Magnetization

Jakub KAPEK, Kévin BERGER, Jean LÉVÊQUE

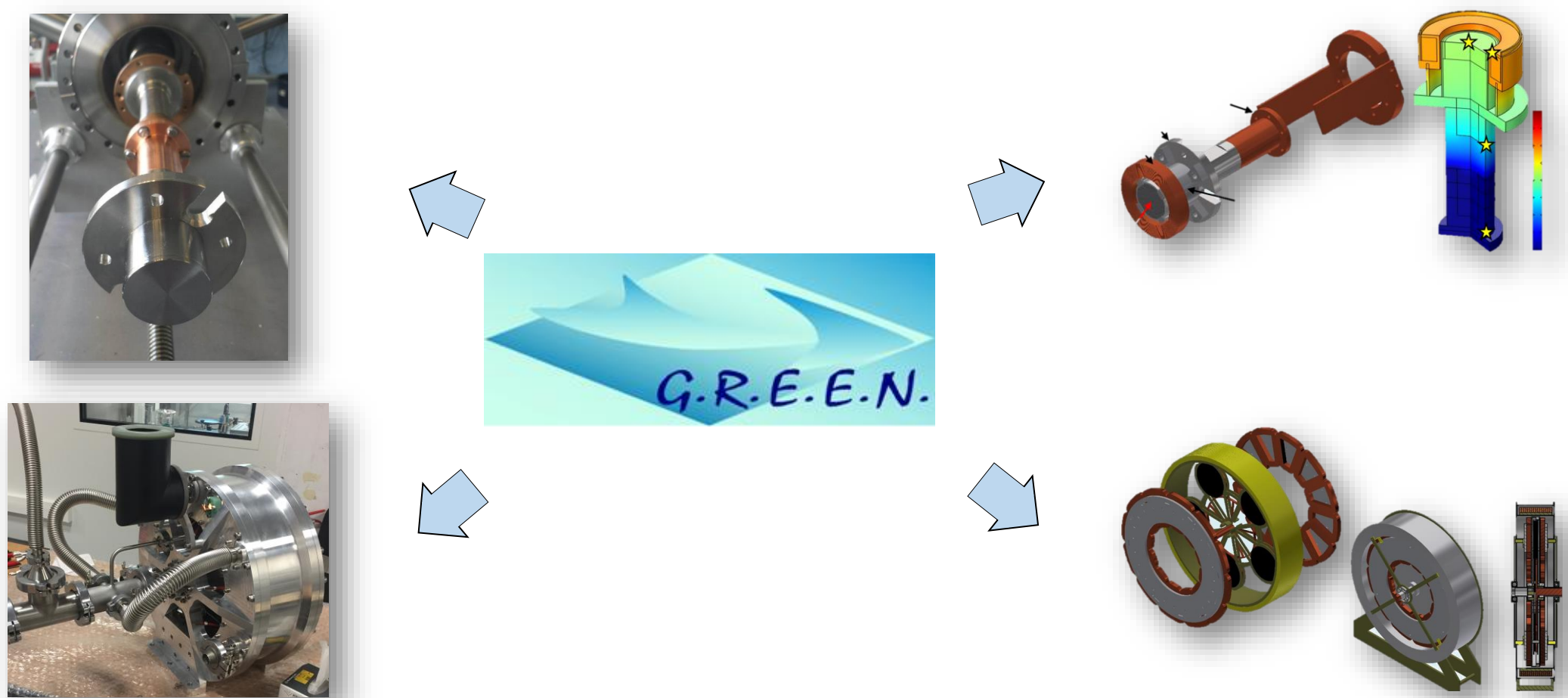
1. Introduction

2. Formulation **A – H**

3. Validation of the formulation **A – H**

4. Summary

1. Introduction



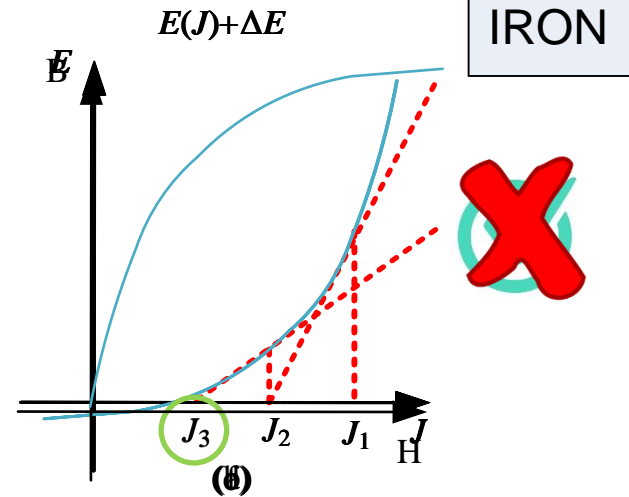
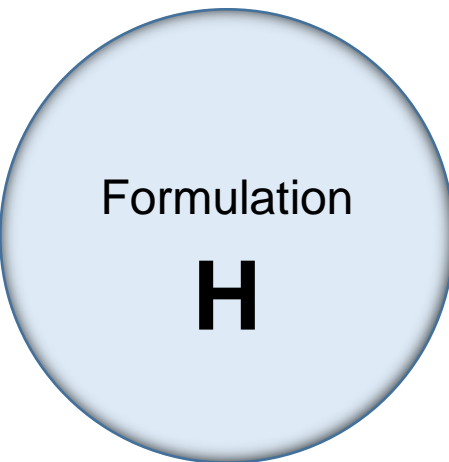
Examples of projects carried out in the GREEN laboratory

1. Introduction

$$\frac{\partial \mu(\mathbf{H})\mathbf{H}}{\partial t} + \nabla \times (\rho \nabla \times \mathbf{H}) = 0$$

$$\begin{cases} \mathbf{E} = \rho \mathbf{J} \\ \mathbf{J} = \nabla \times \mathbf{H} \\ \nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \\ \mathbf{B} = \mu(\mathbf{H})\mathbf{H} \end{cases}$$

Newton's method

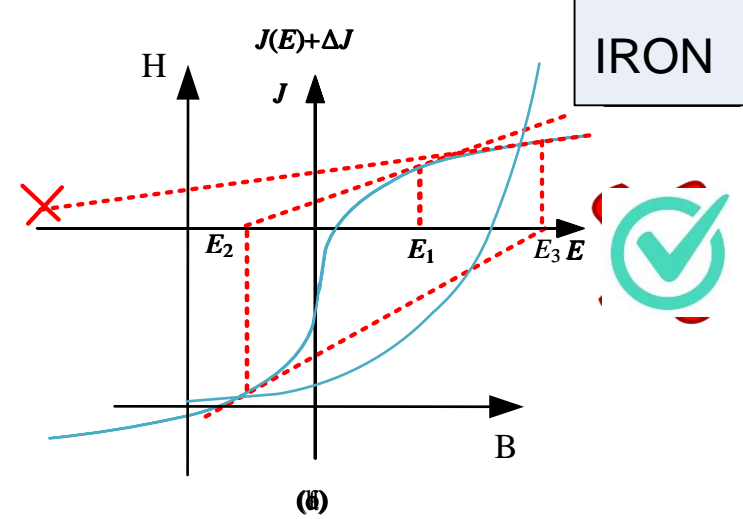
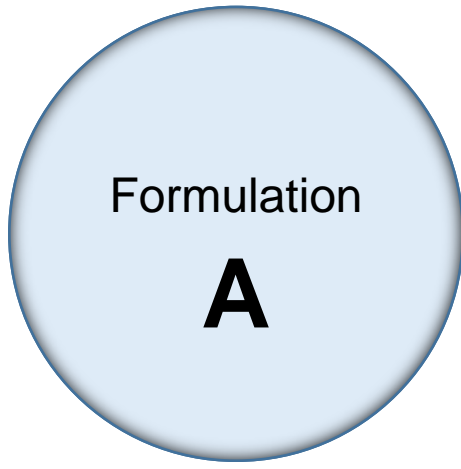


- Recommended for superconductor problems

$$\sigma \frac{\partial \mathbf{A}}{\partial t} + \nabla \times \left(\frac{1}{\mu(\mathbf{B})} \nabla \times \mathbf{A} \right) = 0$$

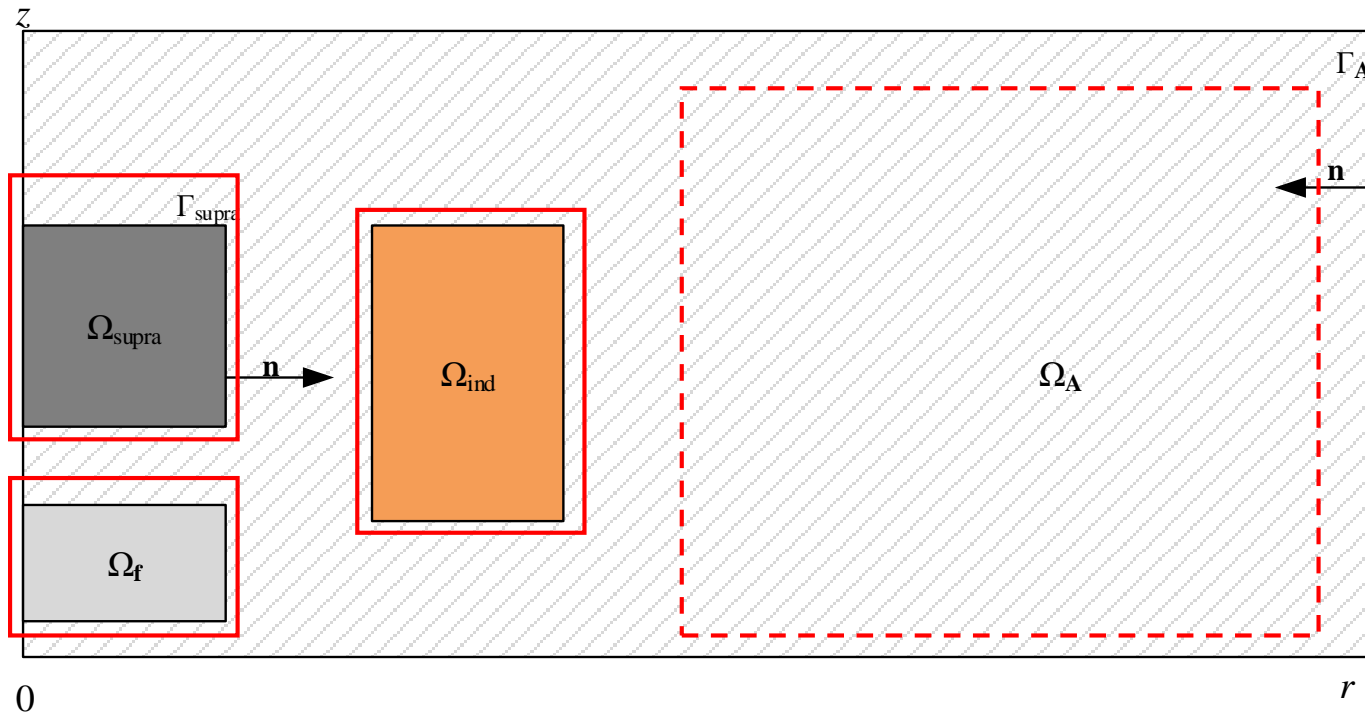
$$\begin{cases} \mathbf{B} = \nabla \times \mathbf{A} \\ \nabla \times \mathbf{H} = \mathbf{J} \\ \mathbf{J} = \sigma \mathbf{E} \\ \mathbf{E} = -\frac{\partial \mathbf{A}}{\partial t} \end{cases}$$

Newton's method



- Recommended for problems with ferromagnetic materials

2. Formulation A – H



Example of a model to apply the **A-H** formulation.

Formulation en **A – H** :

$$\left\{ \begin{array}{l} \nabla \times \left(\frac{1}{\mu_0} \nabla \times \mathbf{A} \right) = \mathbf{J}_{\text{app}}, \quad \text{dans } \Omega_{\text{ind}}, \end{array} \right.$$

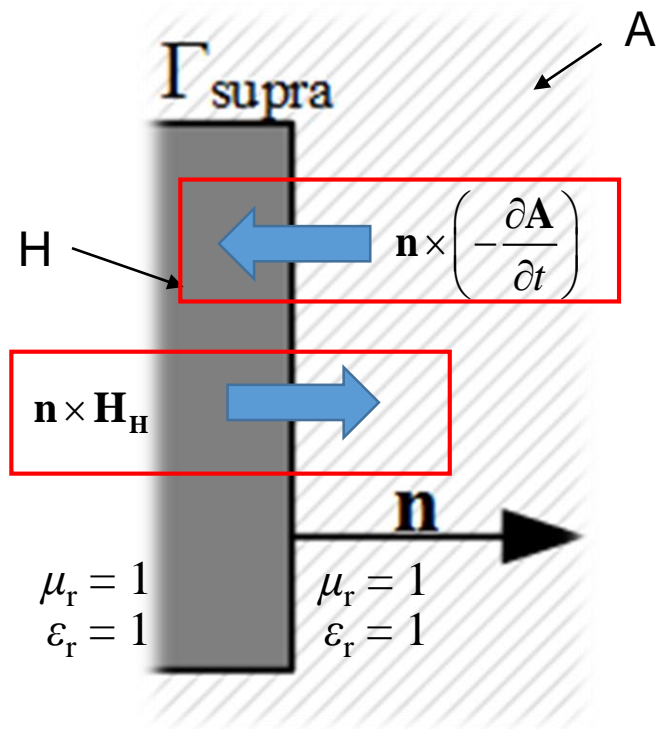
$$\left\{ \begin{array}{l} \nabla \times \left(\frac{1}{\mu(\mathbf{B})} \nabla \times \mathbf{A} \right) = 0, \quad \text{dans } \Omega_f, \end{array} \right.$$

$$\left\{ \begin{array}{l} \nabla \times \left(\frac{1}{\mu_0} \nabla \times \mathbf{A} \right) = 0, \quad \text{dans } \Omega_A, \end{array} \right.$$

$$\left\{ \begin{array}{l} \mu_0 \frac{\partial \mathbf{H}}{\partial t} + \nabla \times (\rho \nabla \times \mathbf{H}) = 0, \quad \text{dans } \Omega_{\text{supra}} \end{array} \right.$$

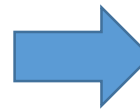
2. Formulation A – H

Interface conditions for electromagnetic fields between two different media:



$$\begin{aligned} \mathbf{n} \cdot (\mathbf{B}_A - \mathbf{B}_H) &= 0 \\ \mathbf{n} \times (\mathbf{E}_A - \mathbf{E}_H) &= 0 \\ \mathbf{n} \cdot (\mathbf{D}_A - \mathbf{D}_H) &= 0 \\ \mathbf{n} \times (\mathbf{H}_A - \mathbf{H}_H) &= 0 \end{aligned}$$

$$\begin{aligned} \mu_r &= 1 \\ \epsilon_r &= 1 \end{aligned}$$

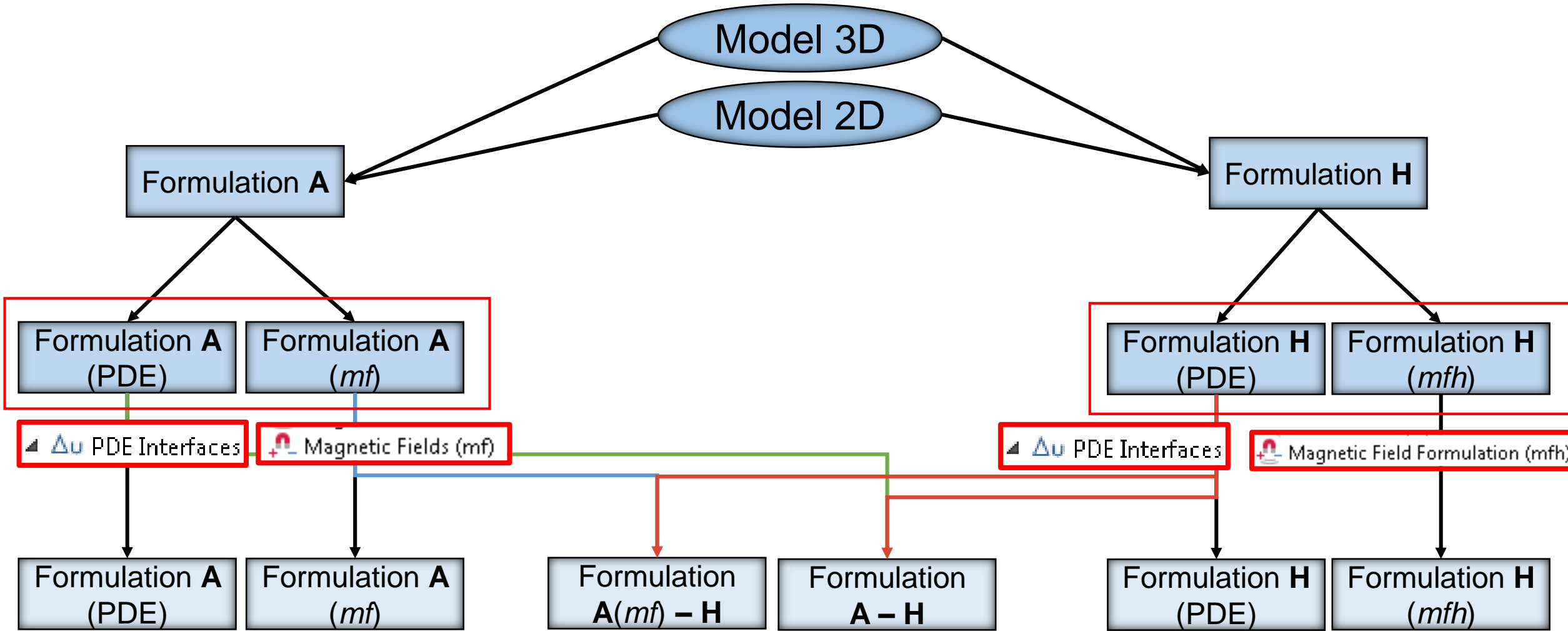


$$\begin{aligned} \mathbf{n} \cdot (\nabla \times \mathbf{A} - \mu \mathbf{H}_H) &= 0 \\ \mathbf{n} \times (-\partial_t \mathbf{A} - \rho \nabla \times \mathbf{H}_H) &= 0 \\ \mathbf{n} \cdot (-\sigma \partial_t \mathbf{A} - \nabla \times \mathbf{H}_H) &= 0 \\ \mathbf{n} \times \left(\frac{1}{\mu} \nabla \times \mathbf{A} - \mathbf{H}_H \right) &= 0 \end{aligned}$$

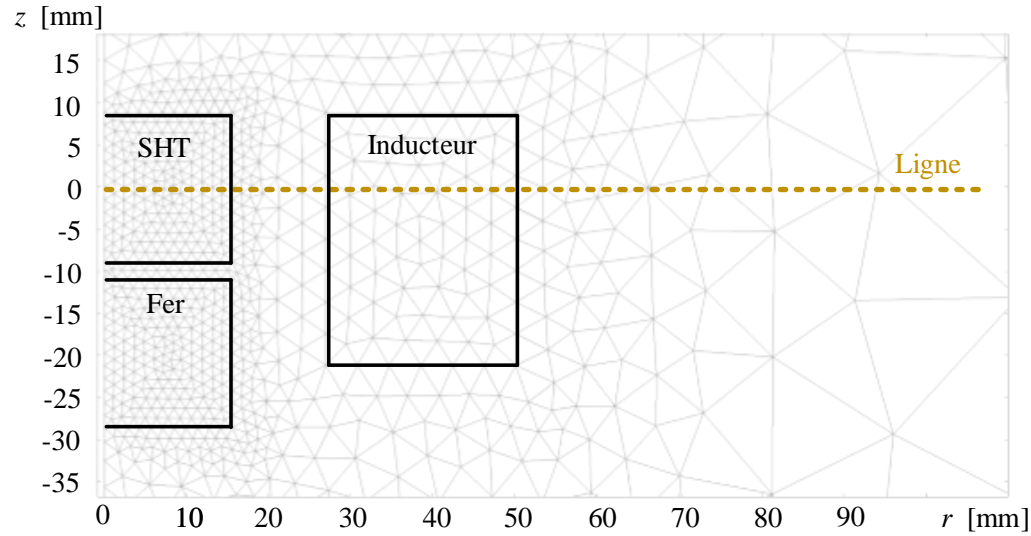
Coupling :

$$\begin{aligned} \mathbf{n} \times \mathbf{H}_H &\rightarrow \mathbf{n} \times \left(\frac{1}{\mu} (\nabla \times \mathbf{A}) \right) \\ \mathbf{n} \times \left(-\frac{\partial \mathbf{A}}{\partial t} \right) &\rightarrow \mathbf{n} \times (\rho (\nabla \times \mathbf{H}_H)) \end{aligned}$$

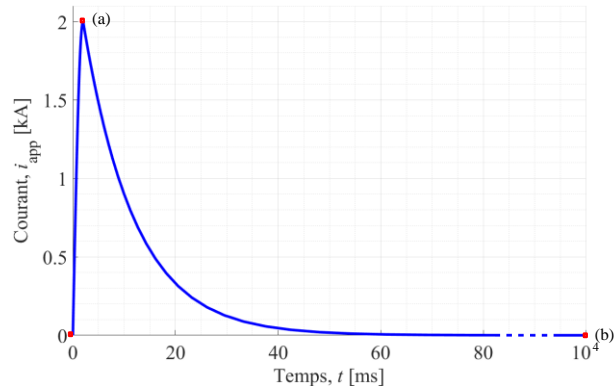
3. Validation of the formulation A – H



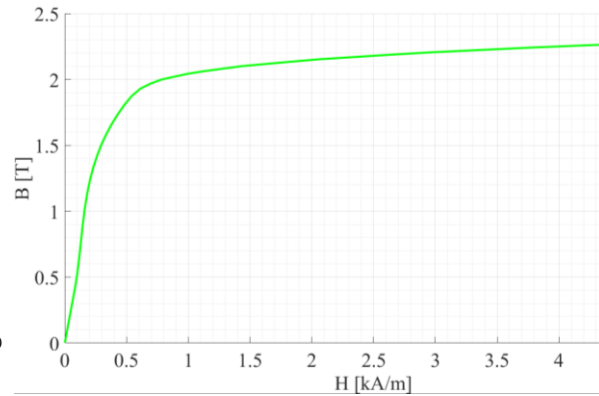
3. Validation of the formulation A – H, 2D



2D axisymmetric problem used to verify the **A – H** formulation.



Form of the current in the inductor.



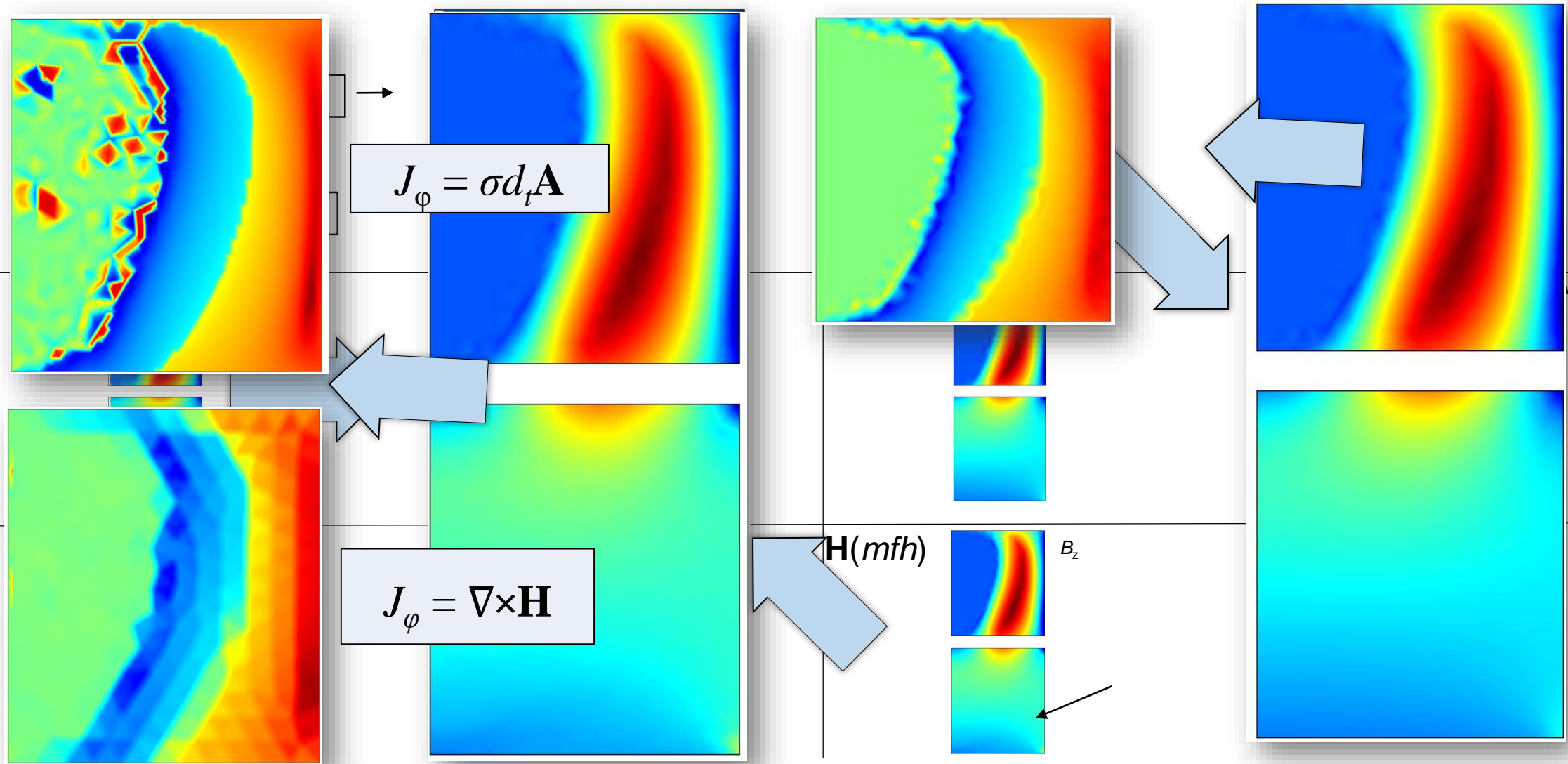
B(H) curve shape of iron-cobalt material.

Electrical and magnetic parameters of the materials used for the verification of the formulation **A – H**.

Symbol	Materials	Electrical parameters	Magnetic parameters
Ω_{supra}	SHT	$\rho = \frac{E_c}{J_c(B)} \left(\frac{\ \mathbf{J}\ }{J_c(B)} \right)^{n(B)-1}$ $\sigma = \frac{J_c(B)}{E_{c0}} \left(\frac{\ \mathbf{E}\ }{E_{c0}} \right)^{\frac{1-n(B)}{n(B)}}$	$\mu_r = 1$
		$n = 21, E_c = 1 \mu\text{V/cm}, J_c = 100 \text{ A/mm}^2$	
Ω_{ind}	Cuivre	$\rho = 1 \Omega \cdot \text{m}$ ^{1) ou 2)} $\sigma = 0 \text{ S/m}$	$\mu_r = 1$
Ω_{fer}	Fer	$\rho = 1 \Omega \cdot \text{m}$ ^{1) ou 2)} $\sigma = 0 \text{ S/m}$	$\mu_r = f(\mathbf{H})$ ¹⁾ $\mu_r = f(\mathbf{B})$ ²⁾
Ω_A	Air	$\rho = 1 \Omega \cdot \text{m}$ ^{1) ou 2)} $\sigma = 0 \text{ S/m}$	$\mu_r = 1$

1) for the formulation in H, 2) for the formulation in A

3. Validation of the formulation A – H, 2D

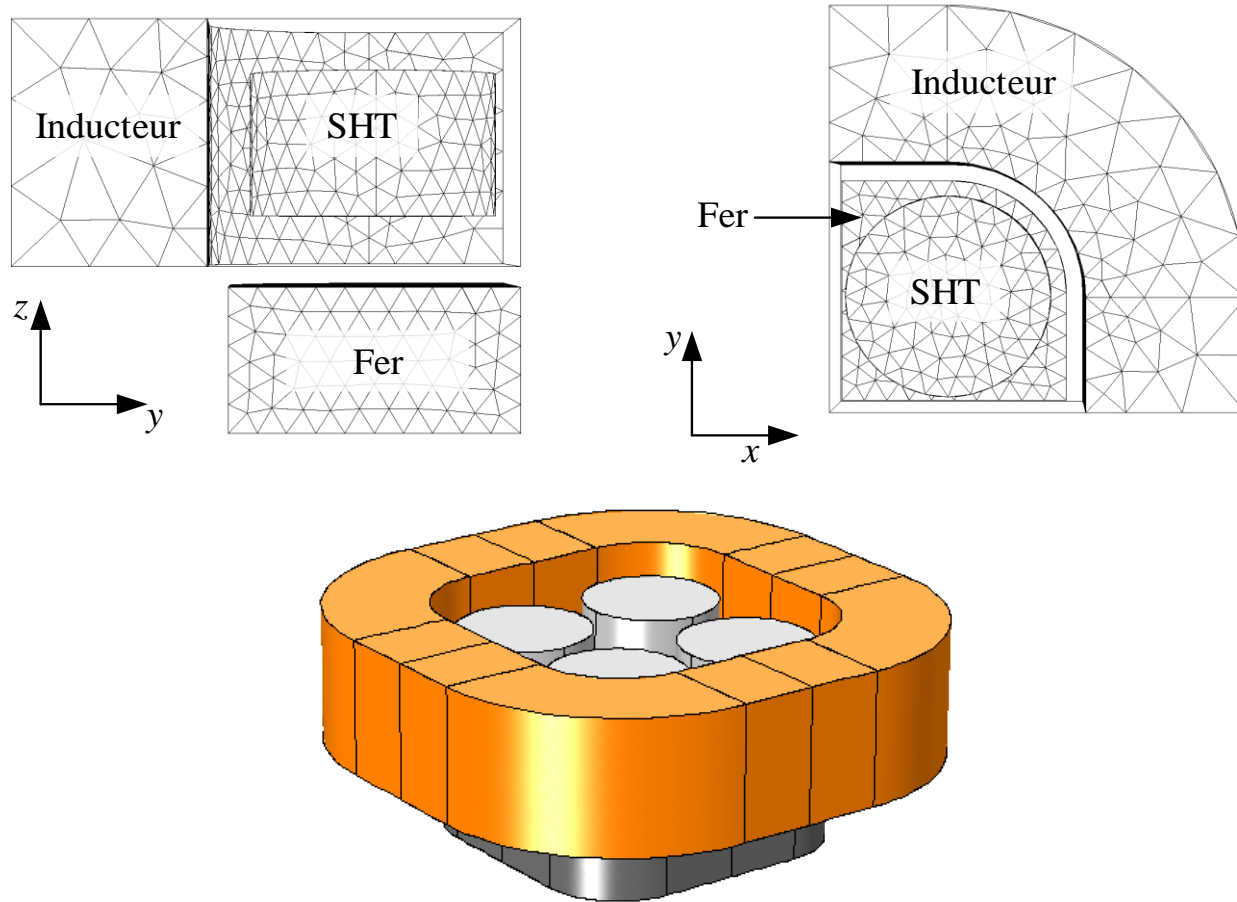


3. Validation of the formulation A – H, 2D

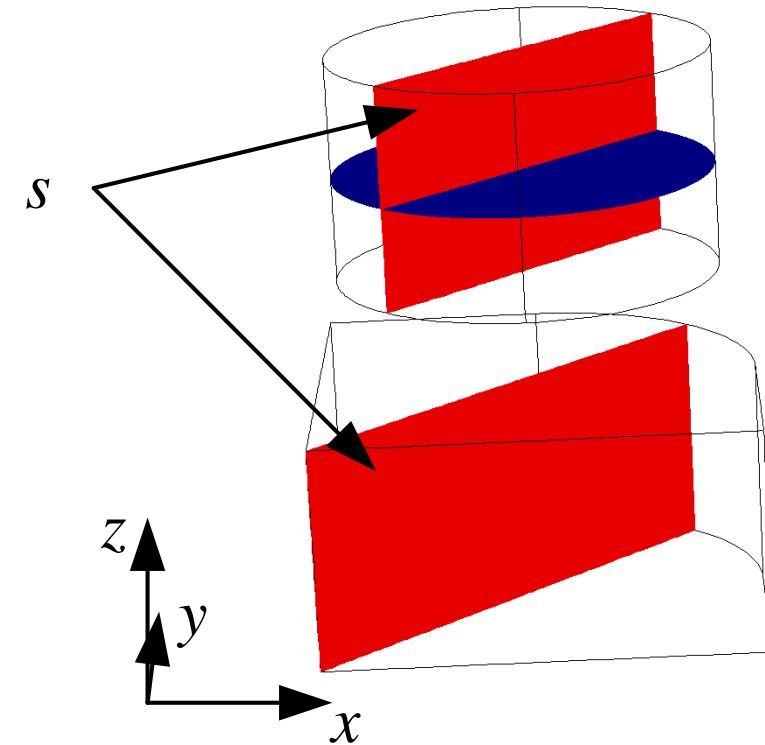
Comparison of computation time and number of degrees of freedom for a 2D axisymmetric problem.

Formulation	Calculation time	Number of degrees of freedom (DDL)
Formulation A – H	3 min 7 s	5 244
Formulation A(mf) – H	3 min 0 s	5 244
Formulation A	28 s	4 150
Formulation A(mf)	21 s	4 150
Formulation H	9 min 49 s	10 242
Formulation H(mfh)	12 min 14 s	10 242

3. Validation of the formulation A – H, 3D

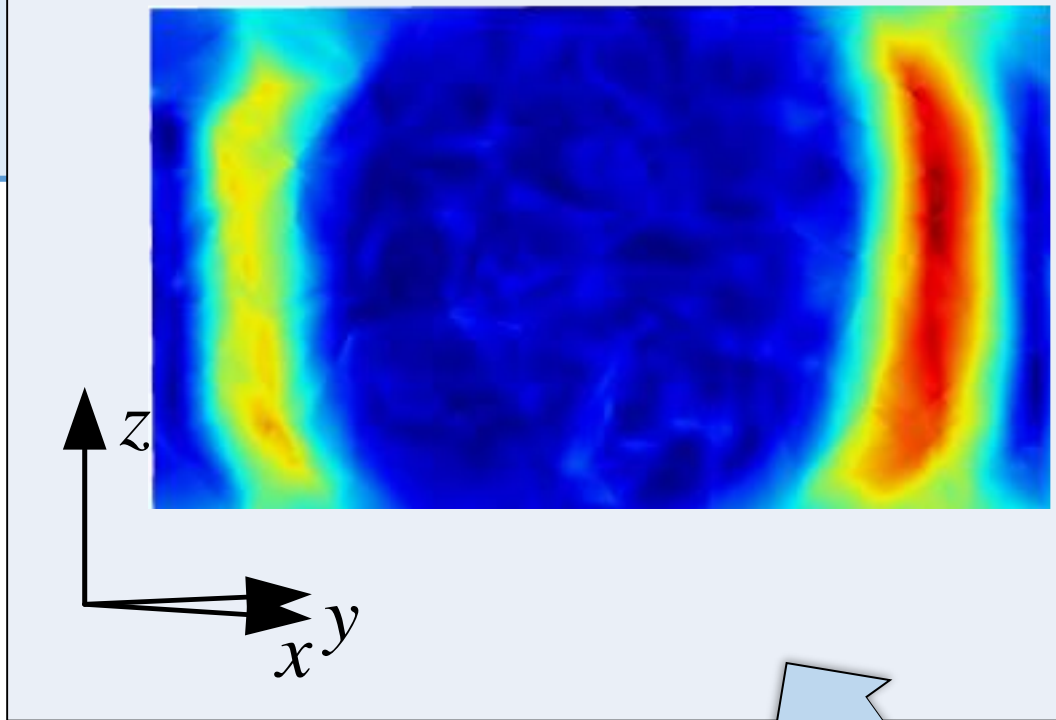


3D model for magnetization of superconductors



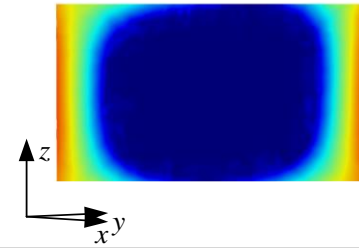
The s-plane cuts both the superconductor and the iron.

on A – H, 3D

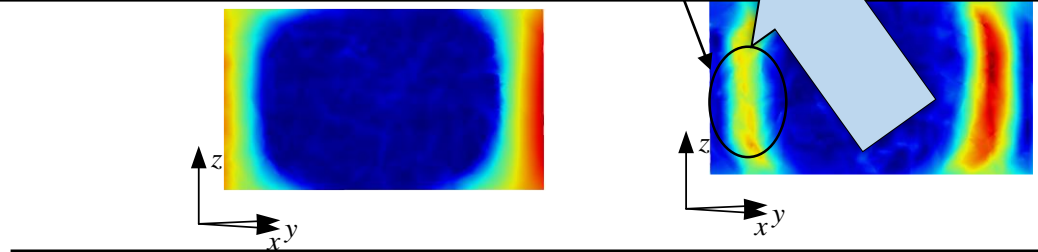
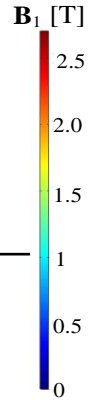
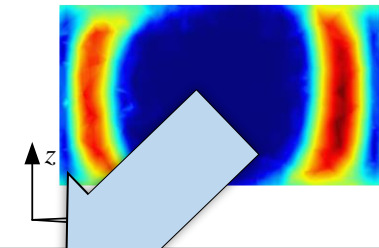


A(mf) – H

B₁, t = 2 ms

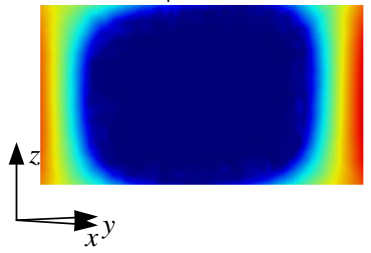


B₂, t = 100 ms

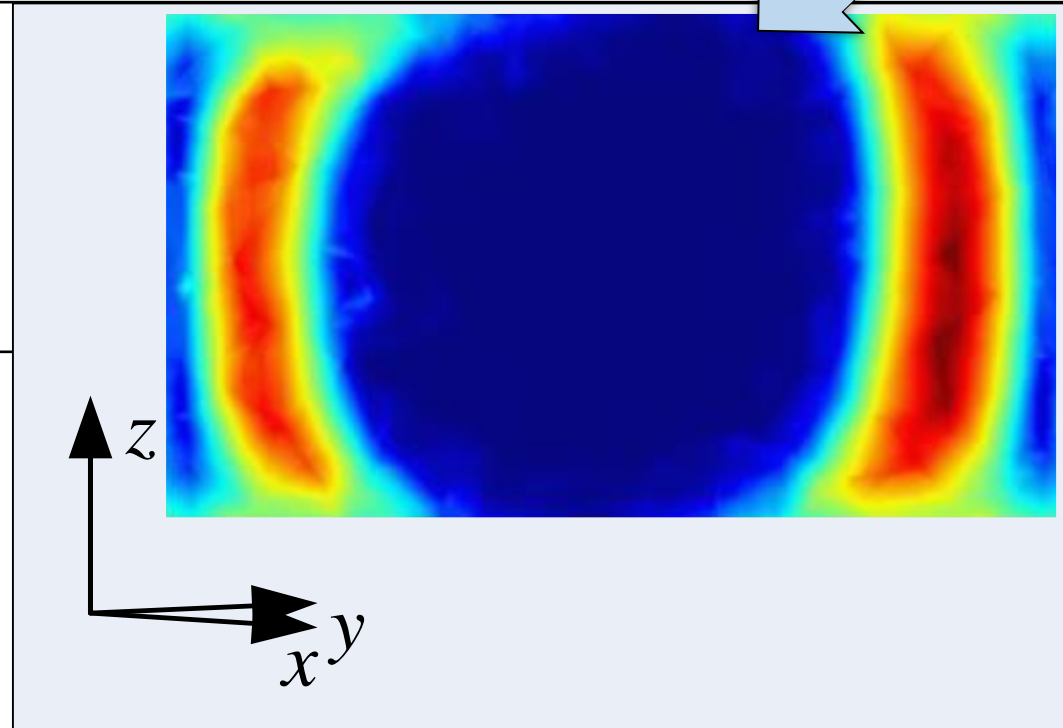
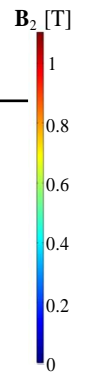
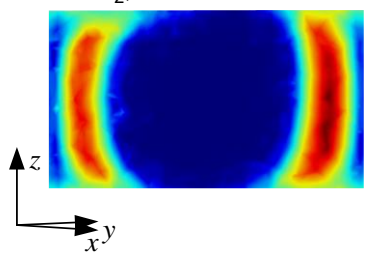


H

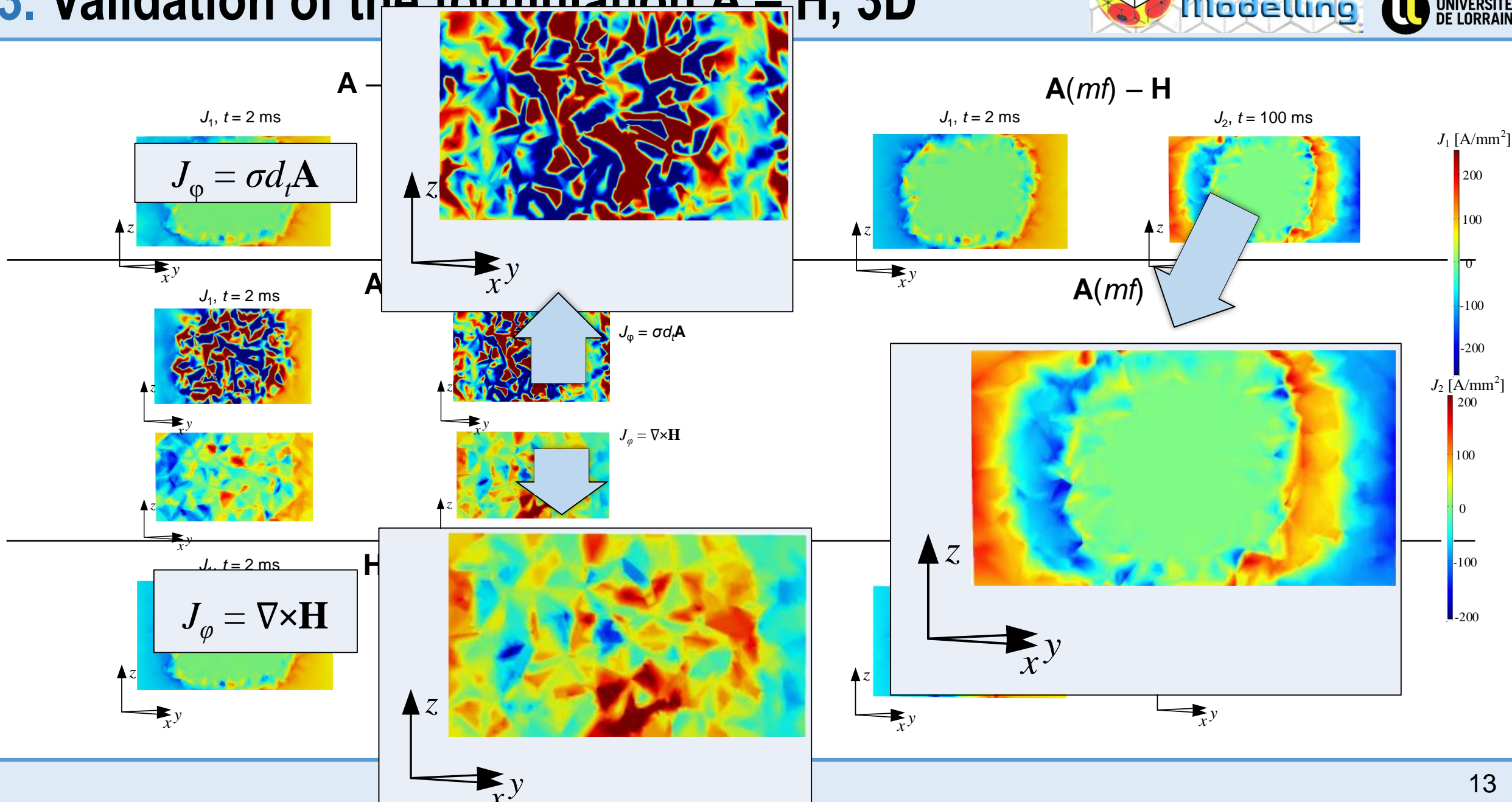
B₁, t = 2 ms



B₂, t = 100 ms



3. Validation of the formulation A – H, 3D



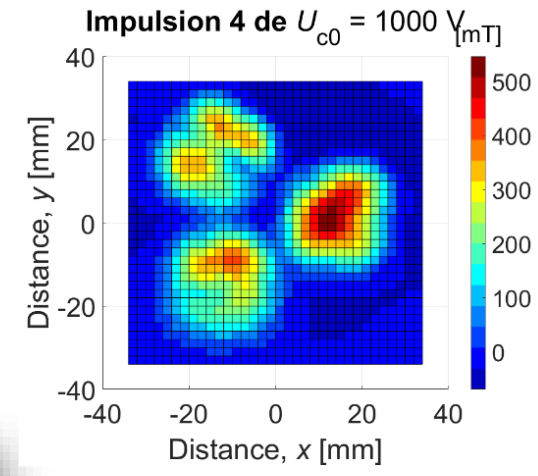
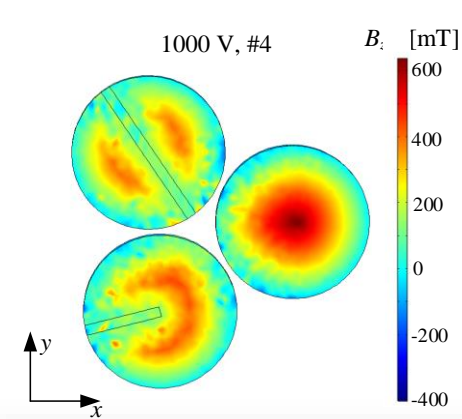
3. Validation of the formulation A – H, 3D

Comparison of the computation time and the number of degrees of freedom for a 3D problem.

Formulation	Calculation time	Number of degrees of freedom (DDL)
Formulation A – H	7 h 20 min 42 sec	141 132
Formulation A(mf) – H	1 j 0 h 8 min 44 sec	199 704
Formulation A	1 j 9 h 27 min 29 sec	126 447
Formulation A(mf)	Not solved	196 264
Formulation H	4 h 7 min 25 sec	196 264
Formulation H(mfh)	5 h 22 min 28 sec	196 264

6. Summary

- 1. The **A – H** formulation in 2D and 3D has been presented
- 2. Good convergence with superconductors
- 3. Potential use in modeling magnetization problems or superconducting electric motors
- 4. The **A – H** formulation was combined with a thermal model and used to simulate the magnetization process of 3 HTS



Thank you for your attention