

Modelling of two topologies of trapped-flux machines using second generation tapes with T-A 3D formulation

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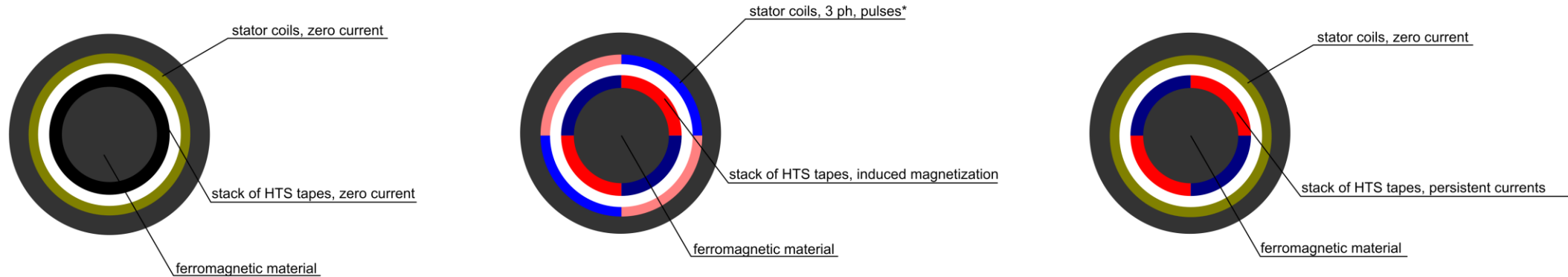
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Overview

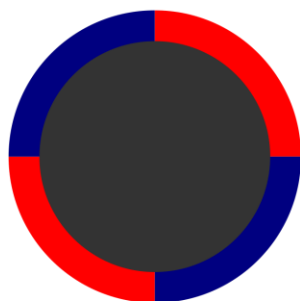
- Various superconducting machines with HTS are investigated on current literature.
- An interesting general topology is the trapped flux superconducting machine:
 - with bulks
 - with stacks of 2G tapes
- FEM simulations: powerful tools to help design superconducting electric machinery.
 - H formulation
 - A-V formulation
 - T-A formulation

Trapped-flux machines with stacks

Partially superconducting machines with stacks of tapes acting as *quasi*-permanent magnet
Magnetization

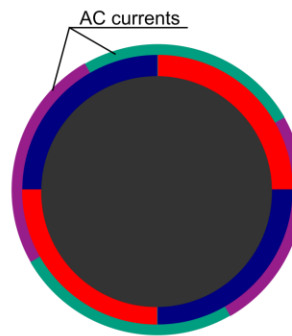


Operation (only rotor)



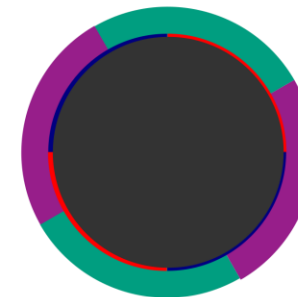
slip = 0

No AC currents, no AC losses



slip \neq 0, low field

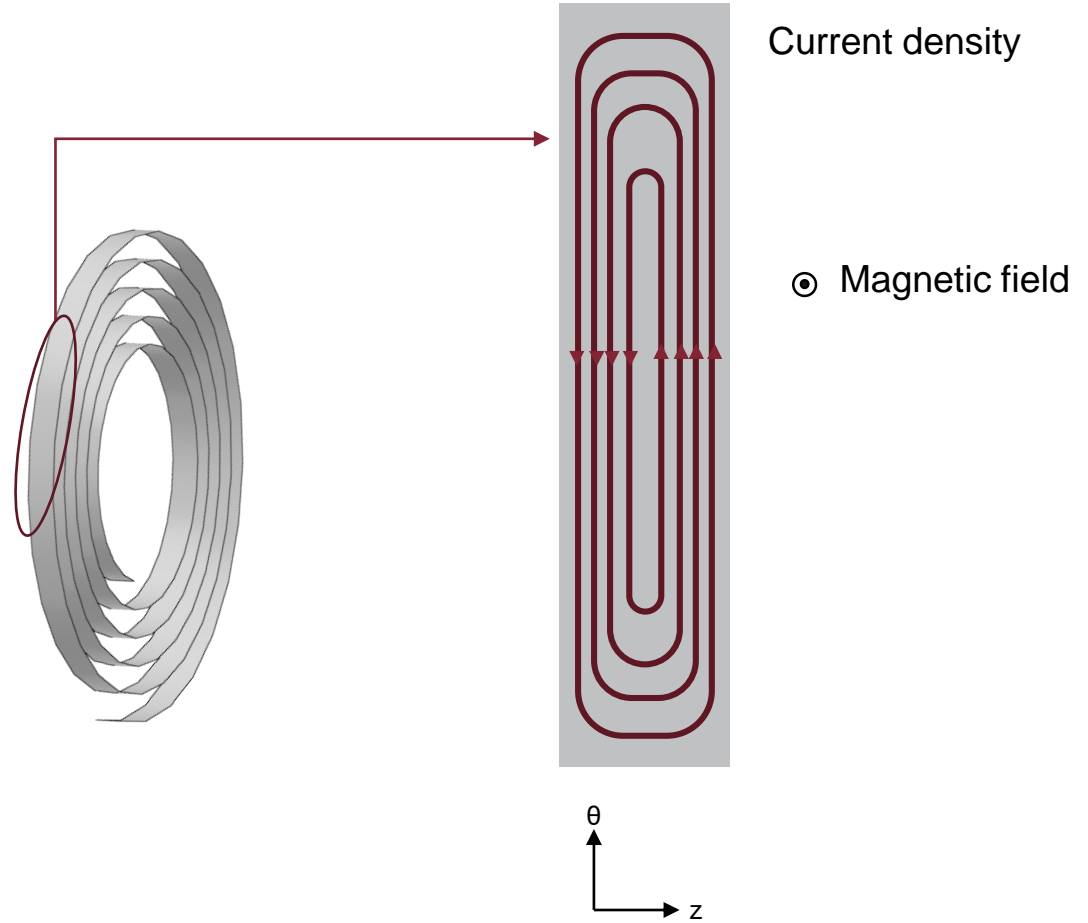
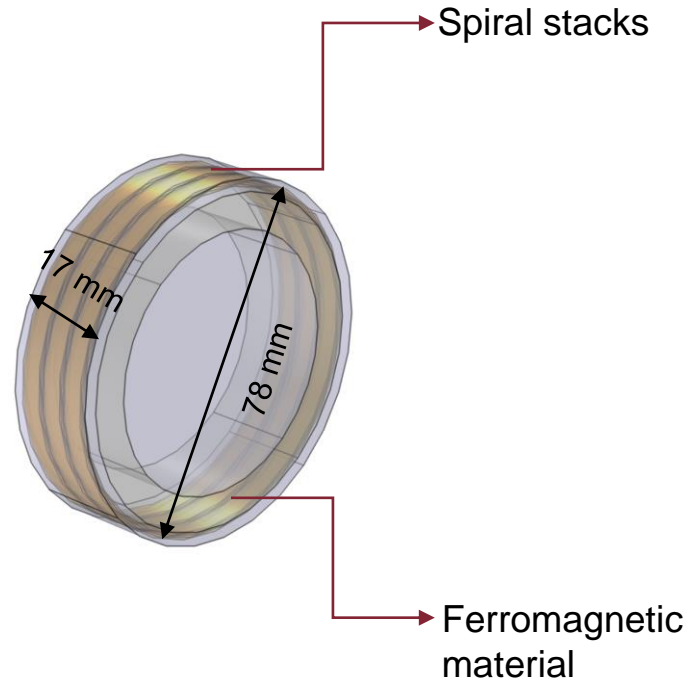
AC currents \ll DC currents, low AC losses



slip \neq 0, high field

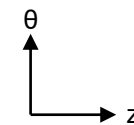
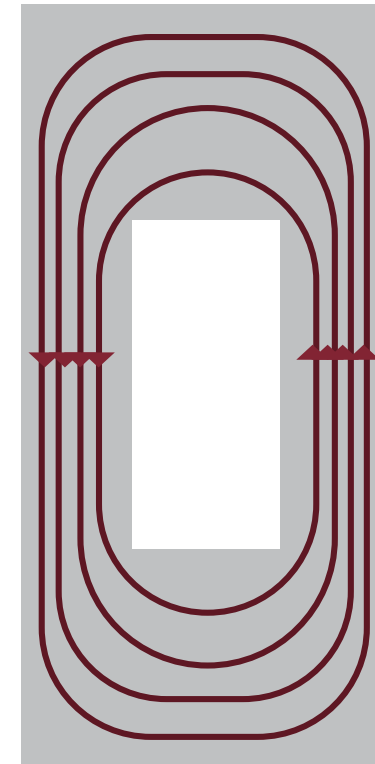
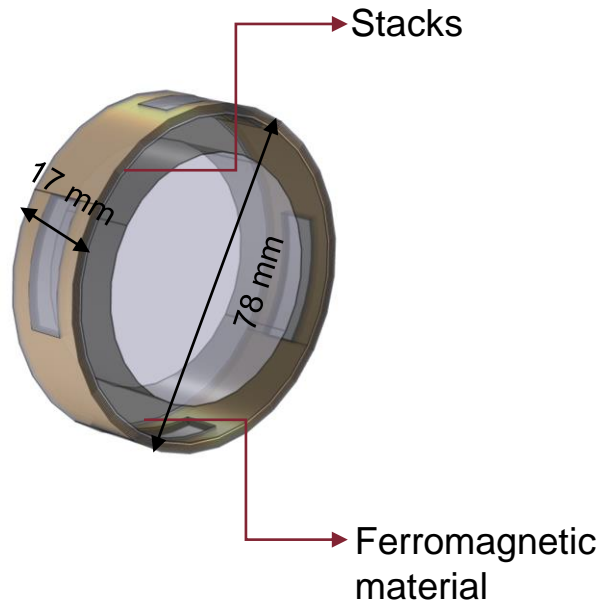
AC currents \gg DC currents, high AC losses

Topology T1



*stator not shown

Topology T2



*stator not shown

Methodology - overview

- Simulation using finite element method (COMSOL Multiphysics) 3D with T-A formulation;
- Objective: compare magnetization capabilities of T1 and T2;
- Method: simulate the response to a pulse of current density applied to the stator forming four magnetic poles and check the current density in the superconducting material after the pulse.

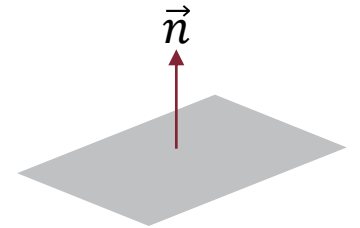
T-A formulation

$$\nabla \times \left(\frac{1}{\mu} \right) \nabla \times \vec{A} = \vec{j}$$

$$\nabla \times \vec{A} = \vec{B}$$

$$\nabla \times \rho \nabla \times (\vec{T} \cdot \vec{n}) = - \left(\frac{\partial \vec{B}}{\partial t} \right) \cdot \vec{n}$$

$$\nabla \times \vec{T} = \vec{j}$$

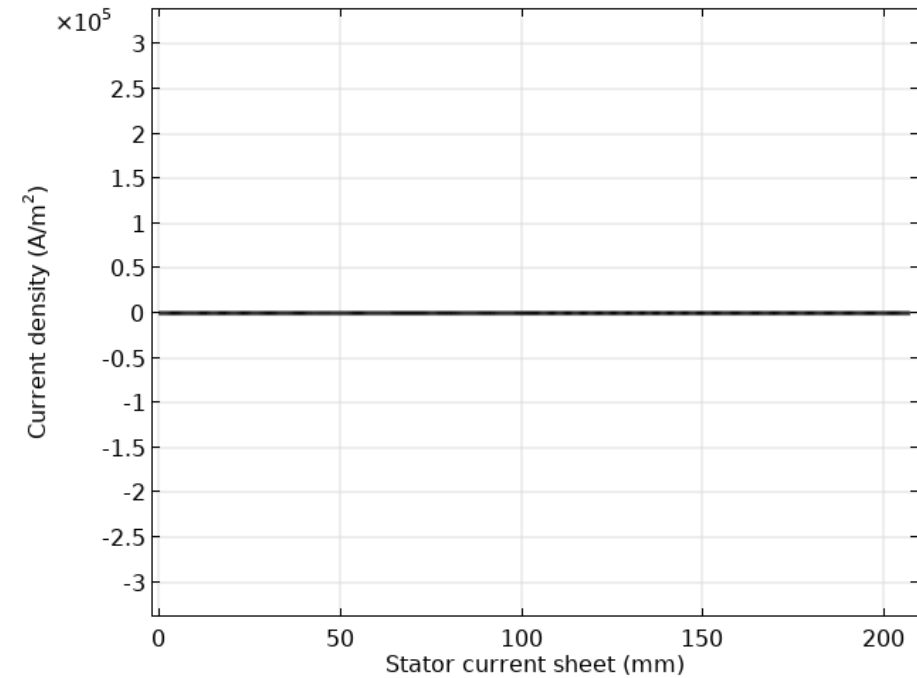
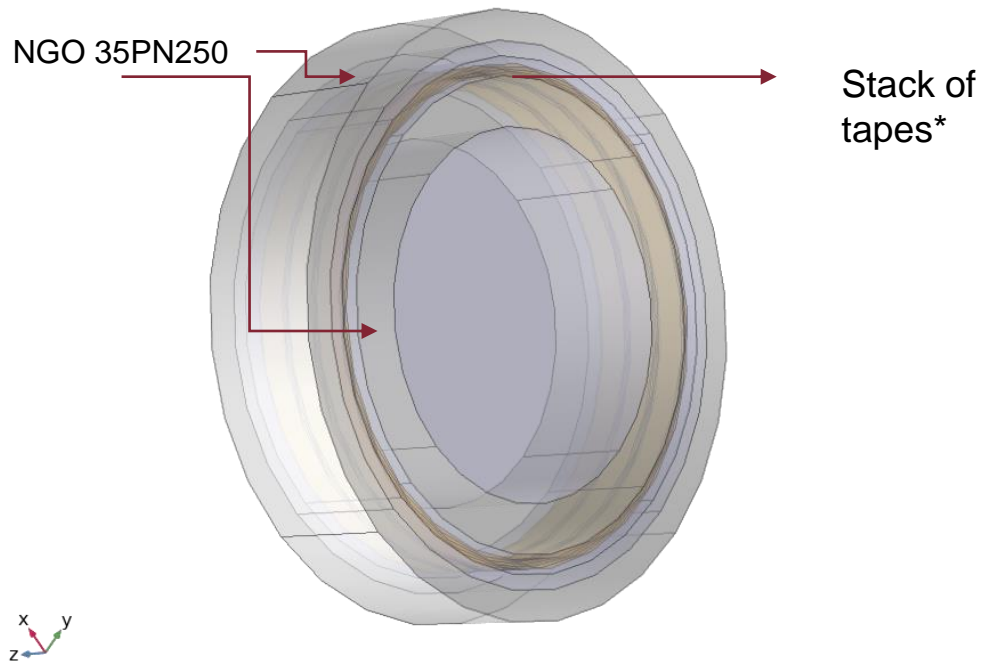


Boundary conditions

$$\vec{n} \cdot \vec{B} = 0$$

$$I_{total} = \oint \vec{T} \cdot d\vec{l} = 0$$

Simulation parameters



*SuperPower advanced pinning model: 4 mm, $I_c @ 0 T = 47 A$
 $I_c(B)$ curve from the HTS tape database @ Univ. of Wellington

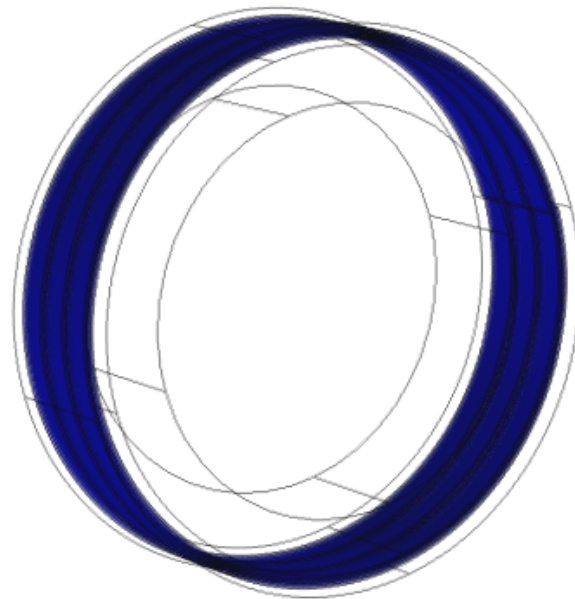
0 – 0.2 s – no current
 0.2 s to 0.4 s – with current
 0.4 s to 0.5 s – no current

Results – T1

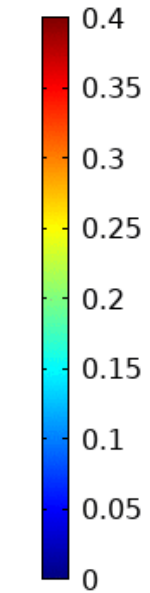
Current density in the stacks (J/Jc)

Time=0 s

Jnorm/Jc

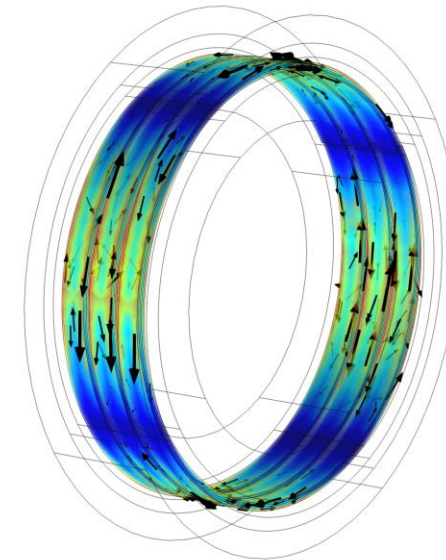


▲ 1.14×10^{-23}



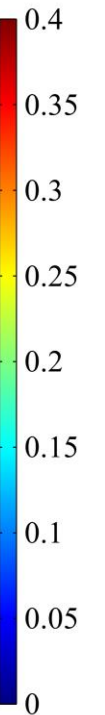
▼ 1.17×10^{-24}

Jnorm/Jc



0.4 s

Pulse ended

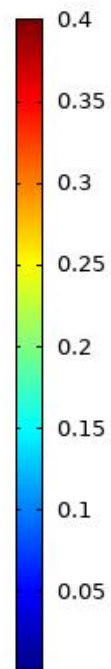


Results – T2

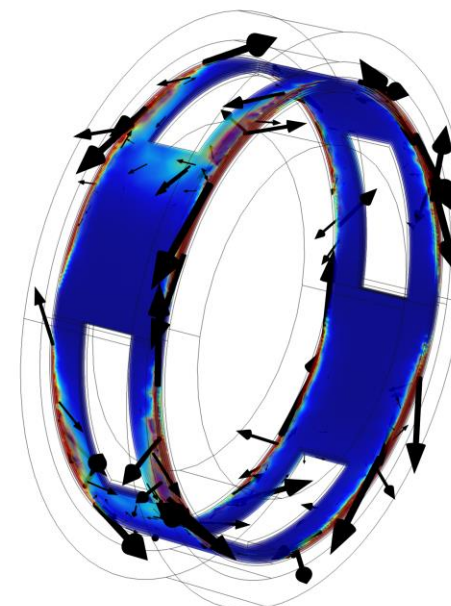
Current density in the stacks (J/Jc)

Time=0 s

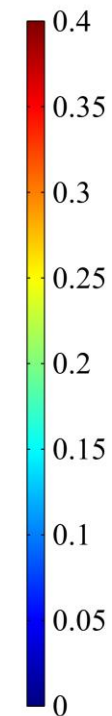
Jnorm/Jc



Jnorm/Jc



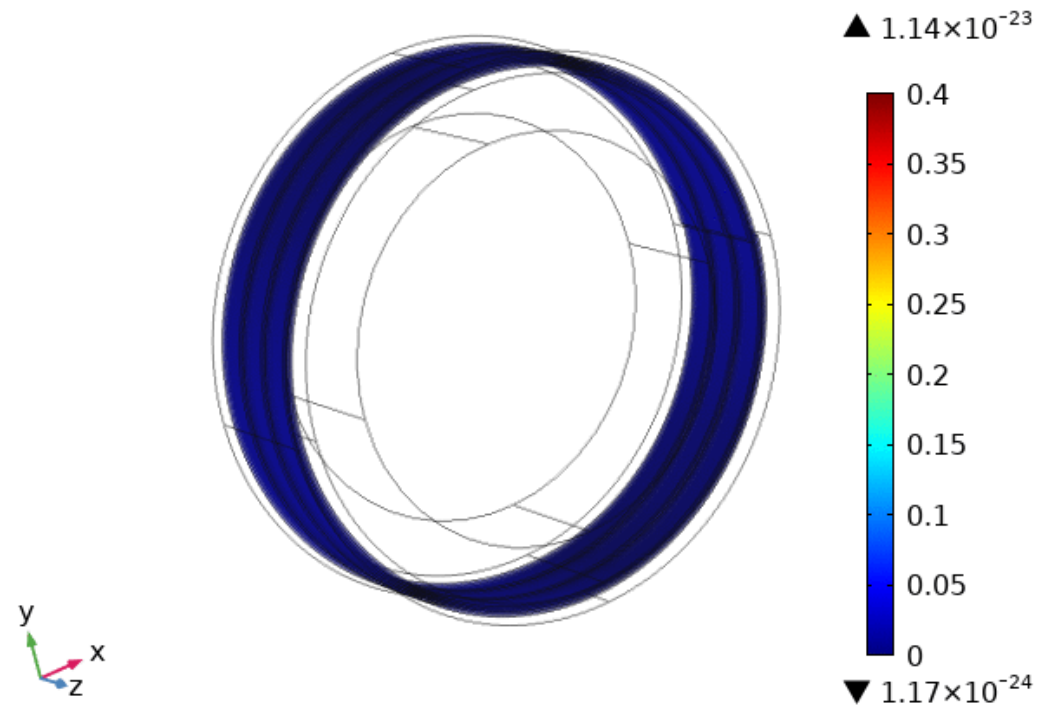
0.4 s
Pulse ended



Comparisons between T1 and T2

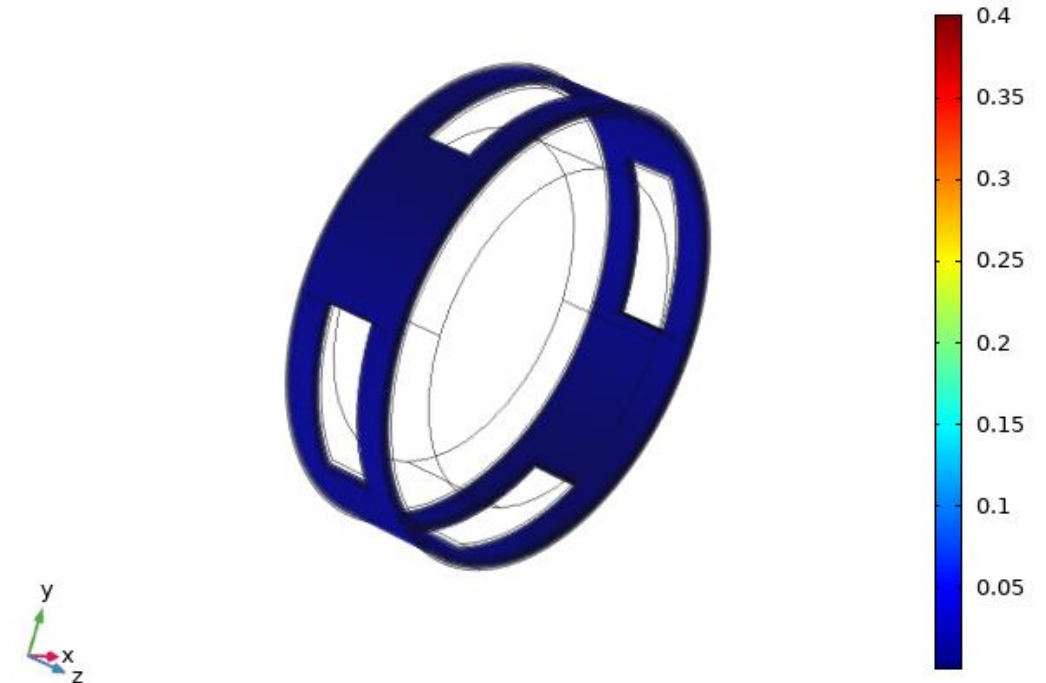
Time=0 s

Jnorm/Jc



Time=0 s

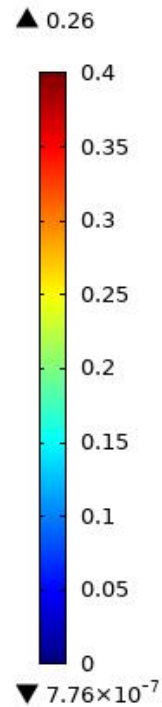
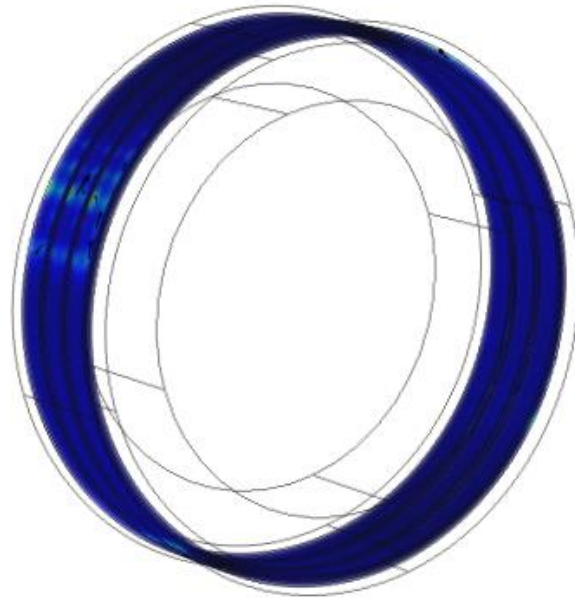
Jnorm/Jc



Comparisons between T1 and T2

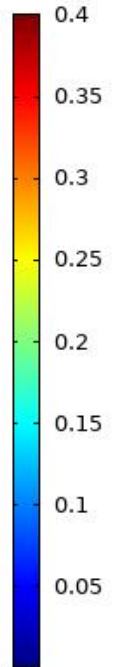
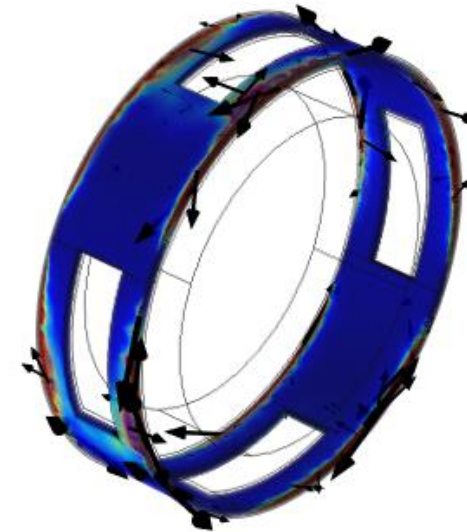
Time=0.5 s

J_{norm}/J_c



Time=0.5 s

J_{norm}/J_c



Conclusions

- Because of its geometric characteristics, topology T2 shows better magnetization capabilities;
- Topology T2 is also more likely to generate reluctance torque;
- Further investigation is needed to determine the optimal configuration for T2.

Thank you!

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